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Performance Motor Controllers

# Operators Manual

## AC1 Controller

DC Conversion

TXT48, PDS, DCS



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**EZ-TXT / TXT48 Conversion Install Manual  
DOC113-033 can be found on our website.**

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# WARNINGS

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## GENERAL WARNINGS

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### Safety Notes:

When working on electric vehicles, sudden unexpected events can occur, it's recommended to:

- Place the drive axle on jack stands—wheels off the floor.
- When working on wiring or batteries, always remove rings, watches and secure dangling clothing/hair/jewelry.
- Use the proper safety equipment, eye protection, and insulated tools.
- Never connect a computer while the vehicle is being charged.
- Disconnect batteries before installing or working on the Alltrax controller.
- Wear safety glasses.
- Because hydrogen can build up due to gassing from the batteries, work in a well ventilated area.
- Make sure the battery pack is fused.
- Do not clean the controller with a high PSI pressure washer.
- When cleaning batteries, take precautions to keep the battery acid from splashing on the controller.

### CAUTION:

It is the installer's responsibility to ensure the correct equipment (i.e. wire, motor, solenoid, fuse etc) is installed in the vehicle. Equipment should be sized correctly for planned usage. Failure to do so could pose a significant risk of explosion, fire, property damage and serious injury or death.

## READ AND SAVE THESE INSTRUCTIONS

# WARNINGS

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## **USABILITY STATEMENT**

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Alltrax Inc's lines of AC Induction and PMAC Motor Controllers are intended for use with brushless motors only. Any application or usage that does not meet these criteria WILL NOT be covered by warranty. Also, any requests for design assistance or technical support outside the scope of the product intended use may be denied. Alltrax assumes no liability for any damage or injury as a result of use of the motor controllers in a non-traction or process motor application. See the warranty at the end of this manual.

**WARNING:** Use of this product for other than these specified uses may be highly dangerous and lead to serious injuries or death.



## **VOLTAGE SETTINGS**

The Alltrax AC1 controller works for a wide range of voltage applications. If you're running aftermarket lithium batteries, a higher voltage than standard or if this is a custom application we highly recommend you check your settings. For detailed instructions you can see our Toolkit operators manual. If the settings aren't correct it can limit torque, limit speed or even prevent operation.



## **THROTTLE SETTING**

It's important to make sure your throttle is correct for your application. The ITS throttle type should **ONLY** be used on DC EZGO applications being converted to the AC1 controller. All factory AC EZGO are 0-5v. Setting the controller for ITS when the car is equipped with a 0-5v throttle can potentially damage the factory throttle.

# WARNINGS

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## OPERATOR SAFETY

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### WARNING:

#### **AFTERMARKET PERFORMANCE UPGRADE — INHERENT RISK / OPERATOR RESTRICTIONS**

This controller is an aftermarket upgrade for golf carts and can significantly increase speed and torque and change handling and stability. When combined with modifications such as lift kits and/or larger tires, the center of gravity may increase and rollover risk may be significantly higher. Improper installation, wiring, setup, programming, incompatible equipment, or unsafe operation can result in loss of control, rollover, serious injury or death, and vehicle/property damage.

Use of this equipment for drag racing, competition, or high-speed operation is strictly prohibited and immediately voids all warranties and technical support eligibility.

Only trained, responsible operators should drive. Do not permit operation by anyone who is impaired by alcohol, drugs, or medication. Where a driver's license is required for the location of operation (including public roads where permitted), the operator must hold a valid driver's license. Minors should operate only where legally permitted and only under direct adult supervision



# WARNINGS

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## OPERATOR SAFETY

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**SAFETY RECOMMENDATION:  
USE PROFILE LOCKOUT  
(available on the FN-KEY Box)  
WHEN OTHERS MAY DRIVE**

If your cart may be operated by other drivers (including minors, guests, employees, or less-experienced operators), we strongly recommend using the optional FN-KEY Box to create and lock a conservative/limited-performance drive profile. The FN-KEY Box's keyed switch allows you to select among user profiles and helps prevent changes to locked settings without the key. Keep the key under adult control. Important: Profile lockout can help reduce the risk of unsafe settings, but it does not eliminate the inherent risks of increased speed/torque, loss of control, rollover, serious injury or death, or damage.

Use only as instructed. Start with conservative settings and test in a controlled area before normal operation. Always follow applicable laws and safe driving practices.



# AC1 SPECIFICATIONS



Model	1 Min (Phase Amps)	Continuous (Phase Amps)
AC1-48650	650	250

**Type:** 3 phase AC

**Operating Frequency:**

**Controller Voltage, KSI & Reverse:** 48v controllers = 16v - 60v  
72v controllers = 16v - 92v

**Operating Temperature:** -20c to 90c

**Environmental Operating Temperature:** -20c to 50c // 0F to 122F

**Standby Current (Power up):** 5mA

**KSI & Rev Pin Input Current:** 200mA max

**Relay Drive Current:** 4A max

**Throttles Supported:** 0-5k, 5k-0, E-Z-GO ITS,  
5k-0 3 Wire, 0-5v, USB  
Throttle, Absolute Mode

**Terminal Bolt Torque:** 60-80 in.lb (5-7ft.lb, 6.77-9.4nm)

**Mounting Bolt Torque:** 15-20 in.lb (1.25-1.75 ft.lb,  
1.7-2.25nm)

## **Terms and Definitions**

**IPM:** *Internal Permanent Magnet*

**SMPM:** *Surface Mount Permanent Magnet*

**KI:** *Integral Gain for PI/PID controllers*

**KP:** *Proportional Gain for PI/PID controllers*

**KD:** *Derivative Gain for PI/PID controllers*

**Quadrature:** *Most common type of Speed Sensor Signal used in AC Induction motor applications*

**Sine/Cosine:** *Commonly used for speed sensors in IPM and SMPM motor applications.*

**ITS:** *Inductive Throttle System, used in DC EZGOs*

**KSI:** *Key switch input, refers to signal voltage from the KEY*

**Roll Detect:** *Is a feature that uses the speed sensor to determine whether or not the cart is moving with no active throttle.*

## **Features**

### **Low Voltage Protection -**

If battery voltage falls below your set Under Voltage limit the controller will shut off the power supply completely to prevent the batteries from getting drained to the point of damaging themselves. If you plug the controller into the toolkit software you will get a large SHUTDOWN warning to notify you of what happened. You can bring power back by cycling the TOW/RUN or plugging your charger back into the cart.

#### ***Trigger Limts -***

*1v for one hour*

*5v under shutdown triggered in 5 minutes*

*10v under shutdown triggered in 1 minute*

### **Encoder Pulses/Revolution Constraint (Quadrature Encoder)**

The maximum encoder frequency the controller will accept is 10 kHz. To determine how fast this constraint will allow the motor to spin, use the equation:

$$\text{Max Speed Encoder Limit} = 600000 / \text{Encoder Size}$$

*(e.g., a motor with 128-pulse encoder can run up to 4587 rpm).*

### **Firmware Max Speed Constraint**

The maximum motor speed the controller will allow is 13,000 rpm.

$$\text{Max Sped RPM Limit} = 13,000$$

### **Alltrax Bluetooth® Mini BLE**

The AC172650 controllers now feature Bluetooth® wireless technology and can communicate with your phone using our AC Toolkit App found on the iOS and Android app stores. For information on use, see document Doc113-054 which should be included in the box with your controller but can also be found on [www.alltraxinc.com](http://www.alltraxinc.com)

# COMPONENTS

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Heavy Duty Contactors



Main Fuse



Heavy Gauge Wires



Alltrax Mini BLE



## ***Contactors (Solenoids)***

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The solenoid is the primary disconnect of the battery pack in the case of the an emergency. In order to be effective, the solenoid needs to be properly rated for the current that will be drawn from the batteries. It is VERY important that the solenoid be rated correctly. It is the only way to disconnect the batteries from the motor/controller loop in case of a failure. Too small of a solenoid increases the likelihood that the contacts will weld together and not be able open.

When installing a new controller, Alltrax recommends the OEM solenoids be replaced with a heavy duty version. See below for suggested sizing of solenoid replacements.

As a regular part of a preventative maintenance plan, solenoids should be replaced every 3-5 years.



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### **Heavy Duty 400A**

*(800-1000A inrush)*

A heavy duty solenoid is required when using any of the AC1 controllers. You need a minimum of 400A continuous and 800A inrush rating.

#### **Recommended Models**

MZJ400 (Shown)

SW200 (Albright)

SOL600

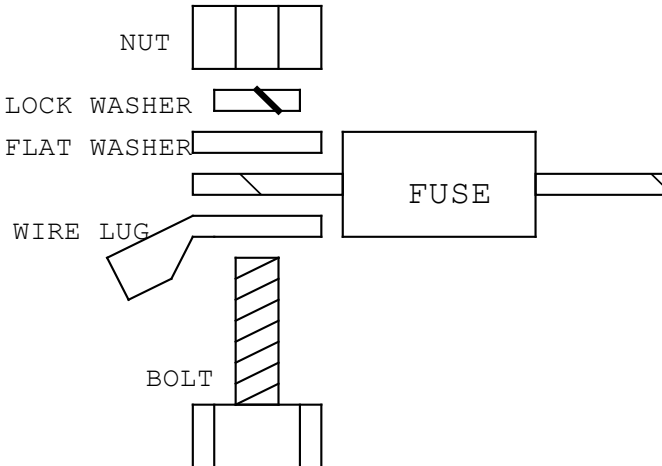
## Fuse

Any application where there is a battery pack, a fuse must be installed. A fuse will open the battery circuit and prevent any serious damage from occurring.

The fuse should be installed on or between the battery terminals. The main battery positive OR main battery negative OR in-between 2 batteries is an acceptable location for fuse installation. The fuse must be rated for pack voltage and fault current.



Controller Amperage	Fuse Style / Rating
650A	ANN / 400A



**Diagram: Fuse terminal hardware**

## **Wiring**

Wiring and battery health in an electric vehicle are very important and overlooked during performance upgrades. Wiring size is important for safety and proper operation of the vehicle. Undersized wires will affect the performance of controllers and can overheat. Wires should be crimped with proper sized terminals and tools to provide a clean low resistance connection.

Controller	Min. Wire AWG Standard Duty	Min. Wire AWG Heavy Duty
650A	2 AWG	1/0 AWG

### **Power Wiring**

When running wiring for the vehicle care must be taken for proper wire routing. Power wiring should be of proper sizing and ran as low in the framework of the vehicle as practical. Lengths of power wire runs need to be kept short and pairs of wires from common circuits should be grouped together to reduce EMC emissions. Secure all power wiring to the vehicle framework.

### **Motor Phase Wiring**

The three phase wires should be kept close to the same length and kept together as they run from the motor to the controller. For optimum reliability don't lay wire across other connections on the controller. Low current wires should not be run alongside the motor wiring or any high current wiring.

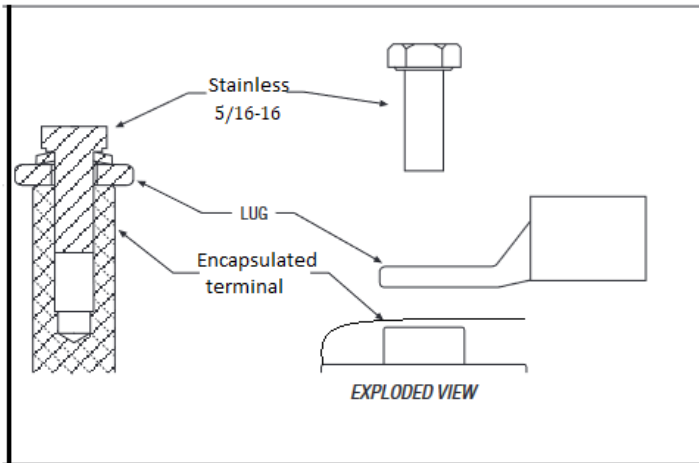
*\*\*\*Never swap motor phase wiring unless key is off and vehicle is not moving\*\*\**

# High Current Connections

TERMINAL	FUNCTION
B+	Battery positive to Controller
B-	Battery negative to Controller
R	Not Used
U	Motor phase U
V	Motor phase V
W	Motor phase W

## LUG ASSEMBLY

The AC controller comes with 5 stainless steel 5/16-16 bolts for holding the high current terminals to the controller.



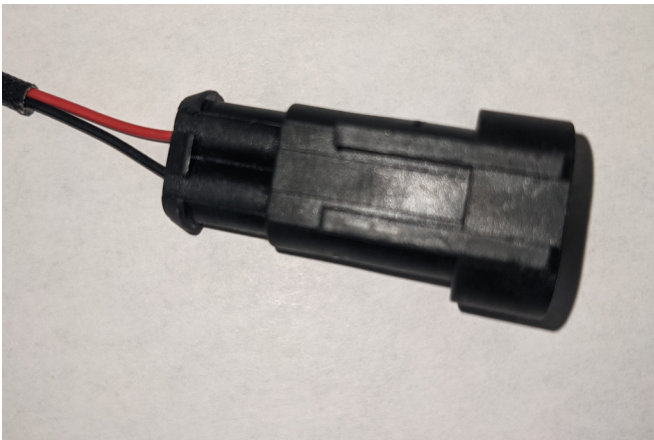
# Low Power Wiring

## Signal Wiring

Signal wires should be kept as short as practical. Care should be taken to protect the wires from sharp edges and rubbing. Consider the use of split loom or braided wire sheathing. Fasten bundles securely to framework. Do not route the signal wires together in the same bundle with power wires.

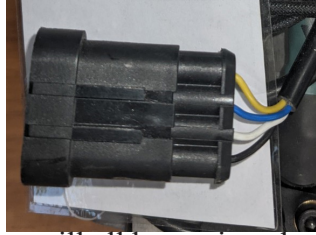
## Temp Sensor

Induction motors come with a two wire temp sensor which the controller uses to monitor internal temps during operation. On DC conversions the temp sensor will run through the same harness connector as your speed sensor.

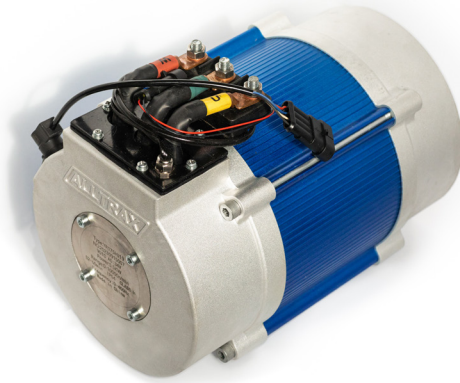


## ***Speed Sensor Information***

The speed sensor is a small group of wires attached to the side of the motor. Induction motors use a Quadrature signal that gives up to 64 readings per minute. Speed sensors are currently required.



Carts that came stock with an AC motor will all be equipped to use the Quadrature sensor. For AC Conversion applications a harness adapter will be used to get the correct signal to the controller without replacing the existing harness.



In the future a sensorless option will be available but currently speed sensors are required for all ACT induction applications.

## ***Speed and Temp sensor cable***



All DC conversion systems will come with a new speed and temp sensor cable to match the new AC motor. We recommend not running this harness parallel to your high current wires. An example would be zip tying them to your large gauge motor wires. Even with shielded wires this can potentially cause issues with the signal. Each connector can only be plugged into one location on the cart/controller but there is a full break down of each connector on the following page. TXT version is 48” long.

### **Encoder Pulses/Revolution Constraint (Quadrature Encoder)**

The maximum encoder frequency the controller will accept is 10 kHz. To determine how fast this constraint will allow the motor to spin, use the equation:

$$\text{Max Speed Encoder Limit} = 600000 / \text{Encoder Size}$$
*(e.g., a motor with 128-pulse encoder can run up to 4587 rpm).*

### **Firmware Max Speed Constraint**

The maximum motor speed the controller will allow is 13,000 rpm.

$$\text{Max Sped RPM Limit} = 13,000$$

# E-Z-GO DCS INFORMATION

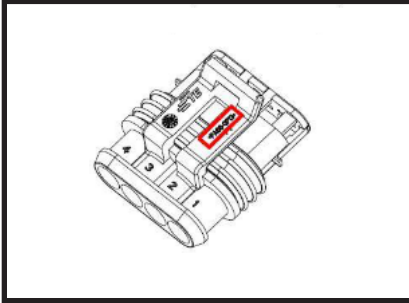
## \*\*\*ATTENTION\*\*\* E-Z-GO DCS OWNERS

To run the AC1 conversion kit you will need to replace your factory wiring harness with an E-Z-GO TXT48 harness. The DCS harness only has 9 wires and would limit functionality of the AC1 controller.



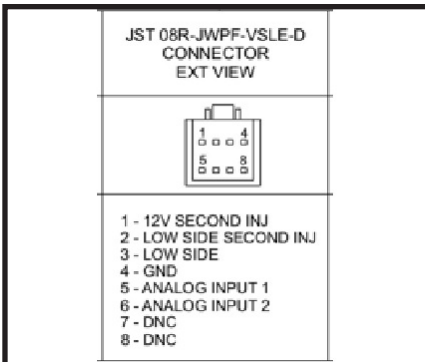
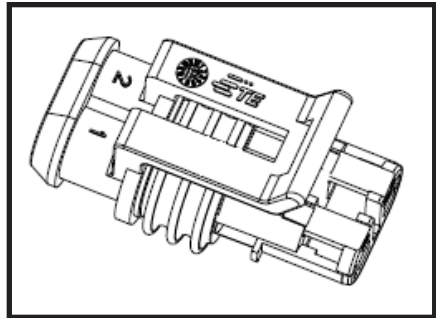
# Wire Harness Pinouts

## Speed and Temp sensor harness connectors Used on all DC conversions



**C3** - TE Superseal 4P connector used for the speed sensor signal of the motor. Water resistant connector.

**C2** - TE Superseal 2P connector used for the motor temp sensor harness. Water resistant connector.



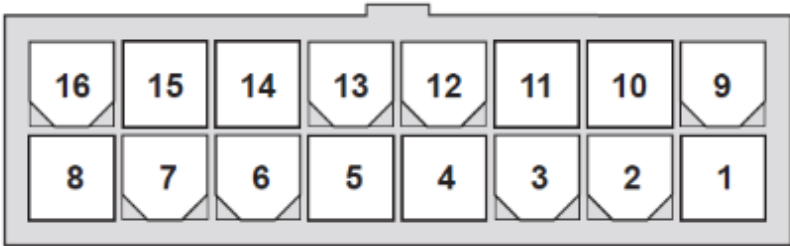
**C1** - JST-JWPF O8 connector used for the controller side connection of the Speed and Temp sensor harness. Water resistant connector.

## ***C1, C2, C3 pinouts for Alltrax harness***

<b>PIN</b>	<b>NAME</b>	<b>DESCRIPTION</b>
<b>**</b>	<b>C1</b>	<b>CONNECTOR</b>
<b>1</b>	Tach Ground	Ground for the speed sensor
<b>2</b>	Tach A	Quadrature A of the speed sensor
<b>3</b>	Tach B	Quadrature B of the Speed sensor
<b>4</b>	+5V Tach	Positive voltage reference
<b>5</b>	Not Used	Not Used
<b>6</b>	Not Used	Not Used
<b>7</b>	Temp Sensor Lo	Motor Temp
<b>8</b>	Temp Sensor Hi	Motor Temp
<b>**</b>	<b>C2</b>	<b>CONNECTOR</b>
<b>1</b>	Temp Sensor Lo	Motor Temp
<b>2</b>	Temp Sensor Hi	Motor Temp
<b>**</b>	<b>C3</b>	<b>CONNECTOR</b>
<b>1</b>	+5V Tach	Positive Voltage Reference
<b>2</b>	Tach A	
<b>3</b>	Tach B	
<b>4</b>	Tach Ground	

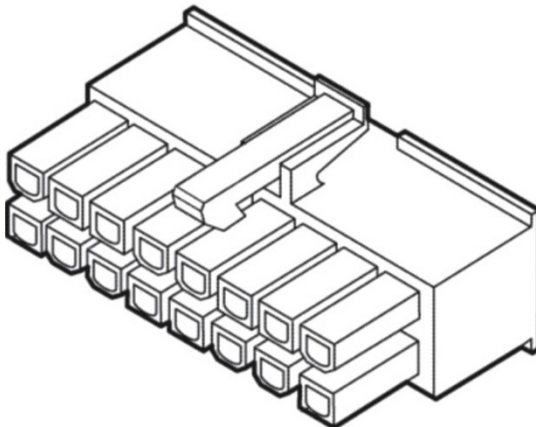
# WIRE HARNESS PINOUT

## 16 pin MOLEX connector E-Z-GO TXT48



*Female side, top down view of controllers connector.*

For DC conversions this connector is used on the stock E-Z-GO TXT48 which came as a 48v. The cart side uses the 16 pin MOLEX 'Mini-fit jr' male housing (see below image) and the 18-24awg crimps.



# 16 PIN TABLE

PIN	NAME	DESCRIPTION
1	Throttle High	Hi side of throttle, white wire
2	Throttle Wiper	Lo side throttle signal, black wire
3	Not Used	Unused on E-Z-GO applications
4	User 1	Not Used
5	Charger Disable	Charge interlock/disable
6	Foot Switch	Throttle activated microswitch
7	Horn Neg	Floating ground for horn
8	Forward	Forward direction signal
9	Run/Tow	Main low power voltage reference
10	Key Switch	Secondary low power voltage reference
11	User 2	Not Used
12	Solenoid Negative	Floating ground for solenoid activation
13	Tach Negative	Unused in DC to AC conversions
14	Tach Out	Unused in DC to AC conversions
15	Tach Reference	Unused in DC to AC conversions
16	Reverse	Reverse direction signal

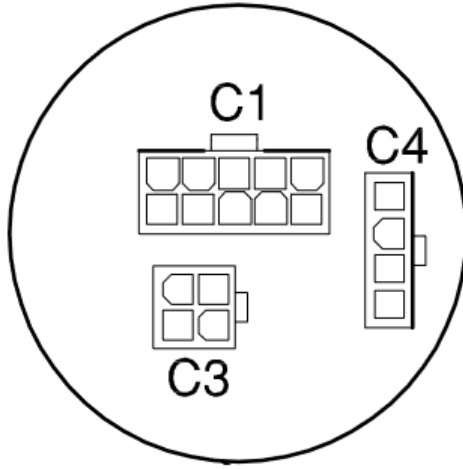
# WIRE HARNESS PINOUT

## PDS MOLEX connectors

Flat 4 pin

Square 4 pin

Rectangle 10 pin



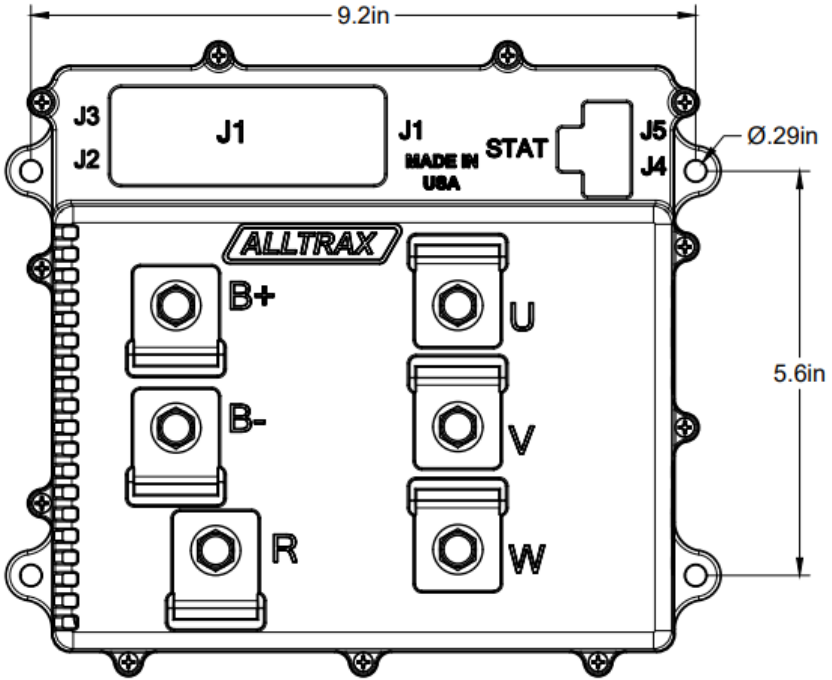
The E-Z-GO PDS connects with 4 harnesses. The three used with the AC1 conversion are showed in the picture above. The missing connector is used for the speed sensor on the stock vehicle. With the Alltrax AC1 conversion you will be using a new speed sensor and temp sensor wire coming directly off the motor (in most cases).

## PDS PINOUT TABLE

PIN	NAME	DESCRIPTION
**	<b>C1</b>	<b>CONNECTOR</b>
1	FnR Feed	Output from controller to FnR switch
2	Reverse	Reverse input from FnR switch
3	Forward	Forward input from the FnR switch
4	Reedswitch Logic	The reedswitch supplies logic power when the charger is disconnected.
5	Logic	Battery reference voltage
6	Solenoid Neg	Lo side logic for controlling solenoid
7	Solenoid Pos	Hi side logic for controlling solenoid
8	KSI logic	Logic signal from key to controller
9	KSI	Signal feed from controller to key
10	Horn	Control signal for reverse buzzer
**	<b>C3</b>	<b>CONNECTOR</b>
1	Logic Input	Reference voltage from controller
2	KSI Logic	Logic input for keyswitch
3	Logic Input	Reference voltage from controller
4	Tow/Run	Tow/Run reference
**	<b>C4</b>	<b>CONNECTOR</b>
1	FS OUT	Footswitch signal output
2	FS IN	Footswitch signal input
3	ITS throttle	Throttle reference
4	ITS throttle	Throttle signal

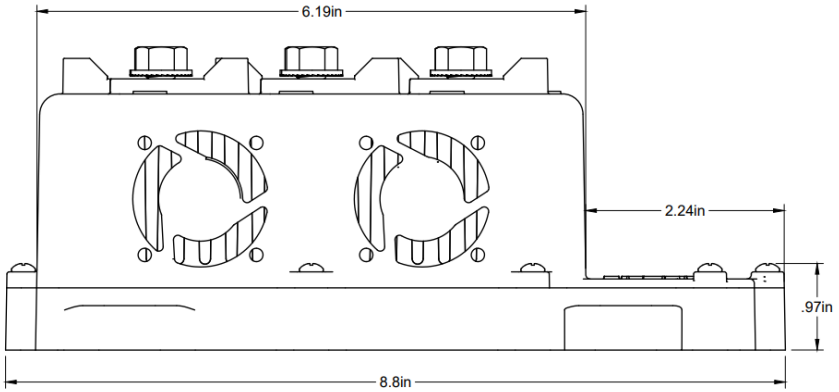
# CONTROLLER DIMENSIONS

## TOP DOWN VIEW

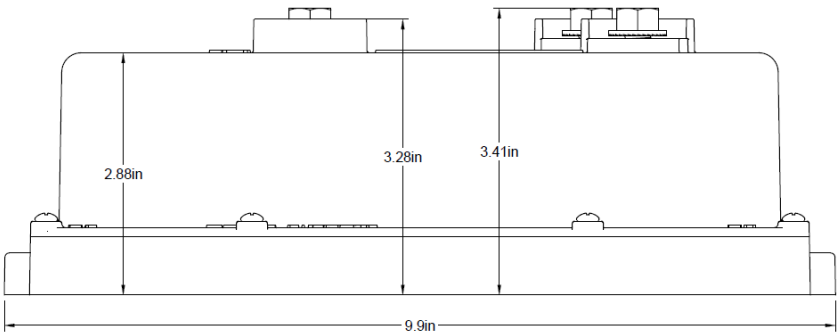


# CONTROLLER DIMENSIONS

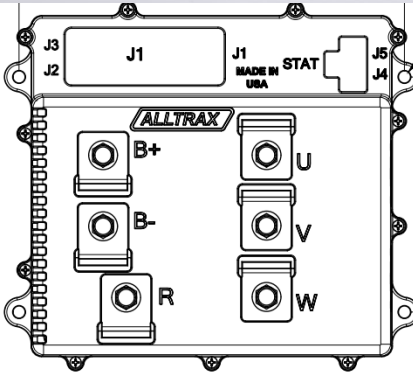
## SIDE VIEW



## FRONT VIEW



# E-Z-GO TXT48 CONVERSION



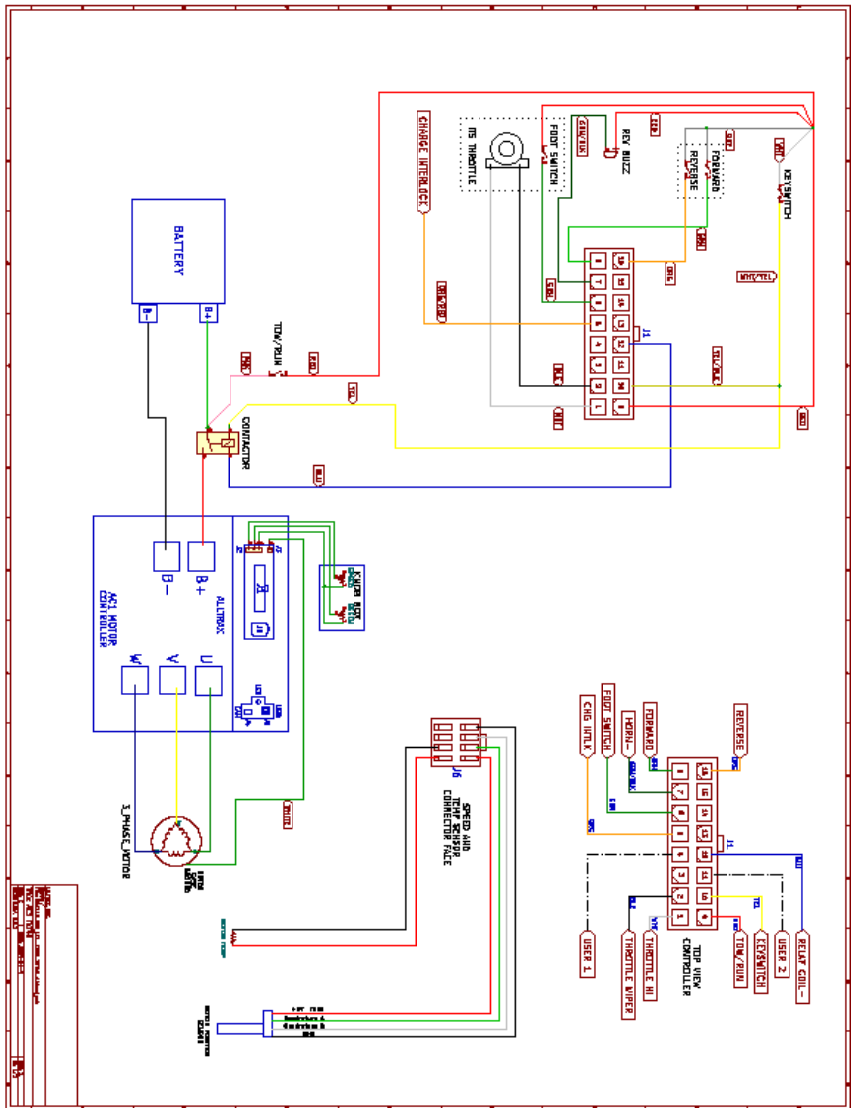
16	15	14	13	12	11	10	9
8	7	6	5	4	3	2	1

**J1** - For an indepth pinout of the harness see pages 20-21 of this manual

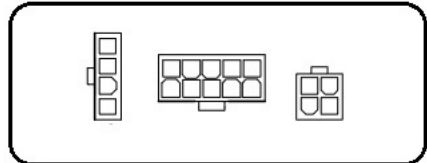
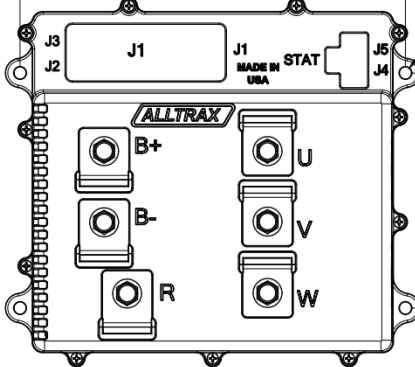
- J1** - Main wire harness connector
- J2** - Personality Switch
- J3** - AC Motor case ground
- J4** - Can Bus
- J5** - Programming port (USB A)

- B+** Positive from Solenoid
- B-** Battery Negative
- R** Not used for conversions
- U** U of the Motor
- V** V of the Motor
- W** W of the Motor

# E-Z-GO TXT48 SCHEMATIC



# E-Z-GO PDS CONVERSION



**J1** - For an indepth pinout of each connector see pages 22-23. Factory 3 pin speed sensor harness not used in AC conversions.

- J1** - Main wire harness connector
- J2** - Personality Switch
- J3** - AC Motor case ground
- J4** - Can Bus
- J5** - Programming port (USB A)

- B+** Positive from Solenoid
- B-** Battery Negative
- R** Not used in conversions
- U** U of the Motor
- V** V of the Motor
- W** W of the Motor

# PROGRAMMING THE CONTROLLER

Controllers ordered for stock configuration come pre-programmed and do not need to be programmed before use. If the user would like to customize their performance or has upgraded their motor and needs a matching motor map the controller can be connected to a computer with a USB A to B, commonly referred to as a “printer cable”.



The USB A to B cable is used to connect your motor controller to your personal computer. Using the free Alltrax Toolkit you can customize your performance to match your needs.

The Alltrax Toolkit software can be  
downloaded from:  
<https://alltraxinc.com/ac-toolkit-software/>  
No purchase necessary

[DOWNLOAD SOFTWARE](#)

## AC Toolkit Software Manual

[AC Toolkit Software Manual](#)

# BLINK CODES

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On power up, the controller will blink out a throttle code and then a Status or Error Code (see below)

## Throttle Type Codes:

1 Green LED Flash	=	2-wire 0-5k throttle
2 Green LED Flash	=	2-wire 5K-0 throttle
3 Green LED Flash	=	0-5V throttle
4 Green LED Flash	=	EZGO ITS throttle
5 Green LED Flash	=	3-wire 0-5k
6 Green LED Flash	=	6 to 10.5 Taylor Dunn throttle
7 Green LED Flash	=	MCOR
8 Green LED Flash	=	Reserved
9 Green LED Flash	=	Pump
10 Green LED Flash	=	USB Throttle
11 Green LED Flash	=	Absolute Throttle
12 Green LED Flash	=	PWM_Throttle

## Brake Type Codes:

1 Green LED Flash	=	2-wire 0-5k throttle
2 Green LED Flash	=	2-wire 5K-0 throttle
3 Green LED Flash	=	0-5V throttle
4 Green LED Flash	=	Reserved
5 Green LED Flash	=	3-wire 0-5k
6 Green LED Flash	=	6 to 10.5 Taylor Dunn throttle
7 Green LED Flash	=	MCOR
8 Green LED Flash	=	Reserved
9 Green LED Flash	=	Reserved
10 Green LED Flash	=	USB Throttle
11 Green LED Flash	=	Absolute Throttle

# BLINK CODES

## Normal Display Status:

Solid Green Light	=	Controller Ready to Run
Solid Red Light	=	Controller in programming mode
Solid Yellow Light	=	Throttle is wide open and the controller is <u>NOT</u> in Current Limit
Blinking Yellow Light	=	Throttle is wide open, but the controller is in Current Limit

## Error Codes:

AC alarm codes flash a sequence of green then red. All alarms are self clearing and will repeat until the error condition has been corrected.

1 Green and 1 Red LED Flash	=	Short Circuit/Output Fault
1 Green and 2 Red LED Flash	=	Battery Under Voltage
1 Green and 3 Red LED Flash	=	Battery Over Voltage
1 Green and 4 Red LED Flash	=	Over temperature
1 Green and 5 Red LED Flash	=	Throttle Power Fault
1 Green and 6 Red LED Flash	=	Pre-Charge Failure
2 Green and 1 Red LED Flash	=	Throttle/Brake Range
2 Green and 2 Red LED Flash	=	Bad Variables
2 Green and 3 Red LED Flash	=	High Throttle Over range
2 Green and 4 Red LED Flash	=	High Throttle Under range
2 Green and 5 Red LED Flash	=	Low Throttle Over range
2 Green and 6 Red LED Flash	=	Low Throttle Under range
3 Green and 1 Red LED Flash	=	Throttle/Brake Range
3 Green and 2 Red LED Flash	=	Bad Variable Set Loaded
3 Green and 3 Red LED Flash	=	Relay Coil Overcurrent
3 Green and 4 Red LED Flash	=	Brake Coil Overcurrent
3 Green and 5 Red LED Flash	=	Reserved Overcurrent*
3 Green and 6 Red LED Flash	=	Horn Overcurrent
4 Green and 1 Red LED Flash	=	Reserved
4 Green and 2 Red LED Flash	=	Reserved
4 Green and 3 Red LED Flash	=	Hardware Failure
4 Green and 4 Red LED Flash	=	Startup Failure
4 Green and 5 Red LED Flash	=	Reserved
4 Green and 6 Red LED Flash	=	Reserved
5 Green and 1 Red LED Flash	=	General Error

# CODE DEFINITIONS

## Error Code Definitions:

- Short Circuit/Output Fault:  
Controller detected a short circuit or other fault on the output circuit.  
Check wiring.
- Battery Under Voltage:  
B+ Voltage lower than Low Voltage Battery Setting. Check pack voltage or program settings.
- Battery Over Voltage:  
B+ Voltage Higher than Over Voltage Battery Setting. Check pack voltage or program settings
- Over temperature:  
Busbar temperature exceeds 90°C. Let controller cool and/or add fan.
- Throttle power Fault:  
This is a 5V fault, if the speed sensor gets damaged this alarm will be one of the alarms triggered. Can also be caused by a fault in voltage based throttles
- Pre-charge Failure:  
B+ voltage and KSI voltage differ by more than 5v. Stuck solenoid.
- Under Temp:  
Busbar Temperature reads less than -20°C
- High Throttle Over range & High Throttle Under range:  
High Side of throttle signal is outside of acceptable window for that throttle type. Check and/or replace throttle. Change throttle type to correct throttle installed on car.
- Low Throttle Over range & Low Throttle Under range:  
Low Side of throttle signal is outside of acceptable window for that throttle type. Check and/or replace throttle. Change throttle type to correct throttle installed on car.
- Bad Variable Set Loaded:  
Alltrax loaded variable data is missing or corrupted. Contact Alltrax
- Throttle/Brake Range:  
The RXV has a “throttle” built into the brake pedal to communicate with the motor brake. This alarm indicates an error in that signal.

# CODE DEFINITIONS

## **Error Code Definitions:**

- Relay coil overcurrent:  
Relay coil has shorted, the wires were attached incorrectly or the suppression control diode is backwards.
- Brake coil overcurrent:  
Short in the brake pedals resistor coil. Presently this can only trigger on EZGO RXV applications
- Horn Overcurrent:  
There is a short in the horn circuit, could be wiring or horn related

# WARRANTY STATEMENT

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Alltrax, Inc., (hereafter Alltrax) warrants that the product purchased is free from defects in materials or workmanship for a period of 2 years from the date of manufacture. This warranty does not apply to defects due directly or indirectly to misuse, abuse, negligence, accidents, repairs, improper installation, submersion, alterations or use contrary to any instructions provided by Alltrax in verbal or written form.

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*“Thank you Nikola Tesla, for a better motor”*

**California Proposition**



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